

Open Loop Hall Effect Current Sensor CYHCS-ST for True RMS Measurement of AC/DC Currents

Current sensors that utilize the Hall effect and open loop measuring principles to convert currents under Test into proportional DC current or voltage outputs via true RMS (TRMS) calculation. The output of the transducer reflects the true RMS value of the current carrying conductor. These sensors enable measurement of DC, AC, pulsed, and irregular waveform currents under electrically isolated conditions. They feature high accuracy, high linearity, high integration, compact size, simple structure, and long-term operational stability.

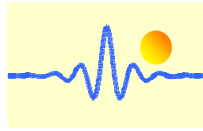
Product Characteristics	Applications
<ul style="list-style-type: none"> • Excellent accuracy • Very good linearity • Light in weight • Less power consumption • Measurement of the true effective value (RMS) • Electrically isolating the output of the transducer from the current carrying conductor • No insertion loss • Current overload capability 	<ul style="list-style-type: none"> • Frequency conversion timing equipment • Various power supply • Uninterruptible power supplies (UPS) • Electric welding machines • Numerical controlled machine tools • Electrolyzing and electroplating equipment • Electric powered locomotive • Microcomputer monitoring • Electric power network monitoring

Electrical Data

Primary Nominal Current I_r (A)	Primary Current Measuring Range I_p (A) at $V_{cc}=24V$	Output Signal (True RMS)	Part number
100	± 150	x=3: 0-5V RMS x=5: 4-20mA RMS	CYHCS-ST100A-xnC
200	± 300		CYHCS-ST200A-xnC
300	± 450	x=8: 0-10V RMS for power supply +20V ~+32VDC	CYHCS-ST300A-xnC
400	± 600		CYHCS-ST-400A-xnC
500	± 750		CYHCS-ST-500A-xnC
600	± 900		CYHCS-ST-600A-xnC
1000	± 1200		CYHCS-ST-1000A-xnC

(n=2, $V_{cc}= +12VDC$; n=3, $V_{cc}=+15VDC$; n=4, $V_{cc}=+20V \sim+32VDC$,
Connector: Phoenix Connector 3.81: C=P3, Phoenix Connector 5.08: C=P5)

Current Consumption	$I_c < 30mA$
Galvanic isolation, 50/60Hz, 1min:	$\geq 3.0kV$
Output Impedance:	$R_{out} < 150\Omega$
Load Resistor:	$R_L > 10k\Omega$
Accuracy at I_r , $T_A=25^\circ C$ (without offset),	$X < \pm 1.0\% FS$
Linearity from 0 to I_r , $T_A=25^\circ C$,	$E_L < 1.0\% FS$
Electric Offset Voltage, $T_A=25^\circ C$,	$V_{oe} = \pm 35mV$
Electric Offset Current, $T_A=25^\circ C$,	$I_{oe} = 4 \pm 0.1mA$
Magnetic Offset Voltage ($I_r \rightarrow 0$)	$V_{om} < \pm 25mV$
Magnetic Offset Current ($I_r \rightarrow 0$)	$I_{om} < \pm 0.1mA$
Thermal Drift of Offset Voltage,	$V_{ot} < \pm 2.0mV/^\circ C$
Thermal Drift (-10°C to 50°C),	T.C. $< \pm 0.1\% /^\circ C$
Response Time at 90% of I_p ($f=1k Hz$)	$t_r < 150ms$
Frequency Bandwidth (-3dB),	$f_b = 20Hz \sim 6kHz$
Used Standard	Q/320115QHKJ01-2016

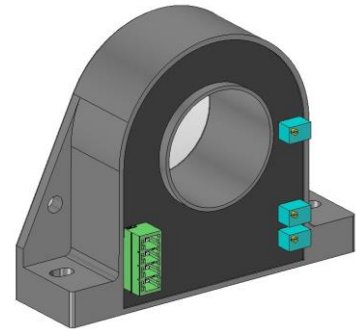
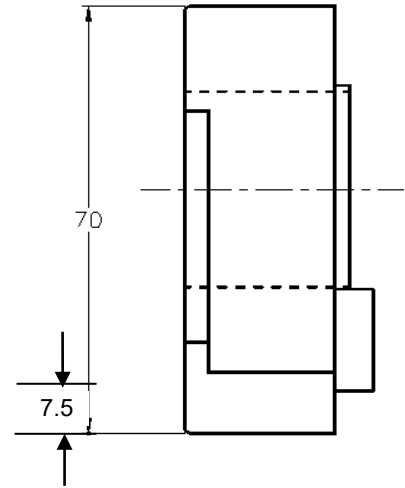
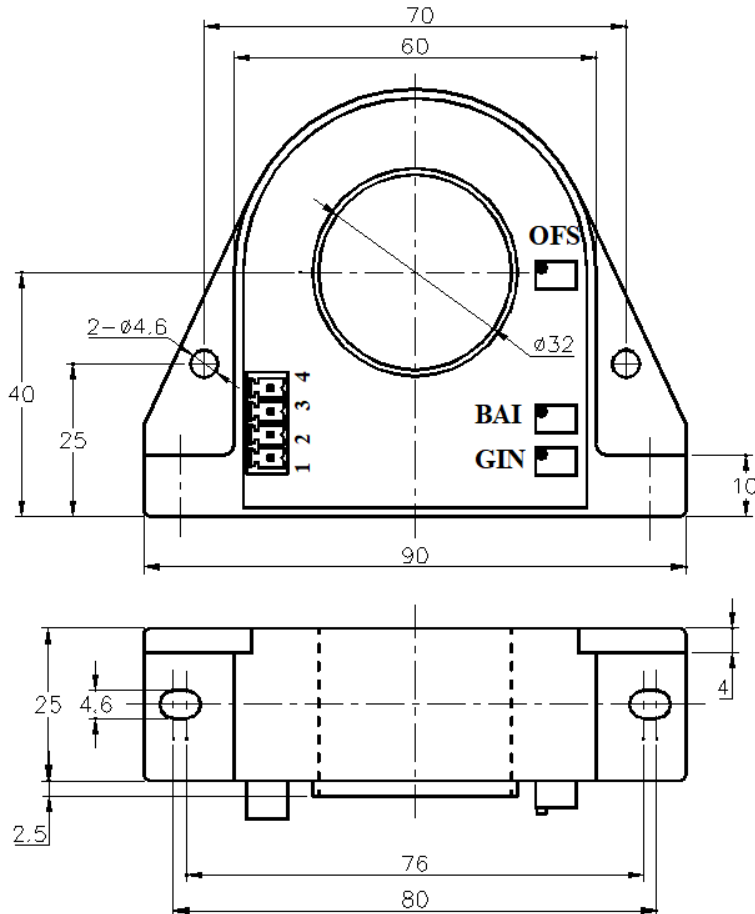


General Data

Ambient Operating Temperature,
Ambient Storage Temperature,
Unit weight,

$T_A = -25^{\circ}\text{C} \sim +85^{\circ}\text{C}$
 $T_S = -40^{\circ}\text{C} \sim +100^{\circ}\text{C}$
250g

PIN Definition and Dimensions - Phoenix Connector 3.81

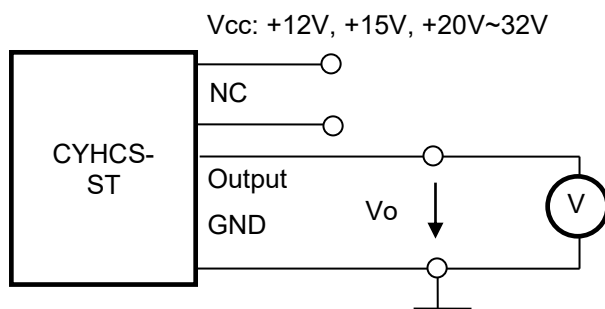


Phoenix Connector 3.81

OFS: Offset Adjustment
BAI: Accuracy adjustment

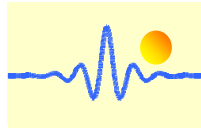
GIN: Gain Adjustment

Connection of Sensors with Voltage Output

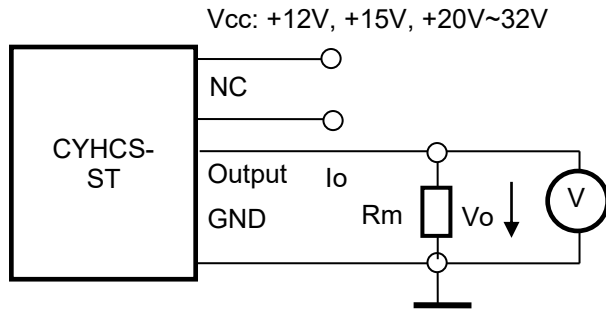


Voltage Output:

1(+): Vcc
2(N): NC
3(Vo): Voltage Output
4(G): GND



Connection of Sensors with Current Output

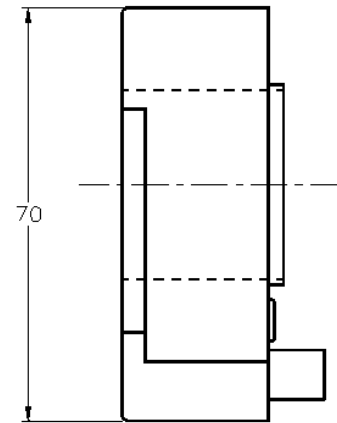
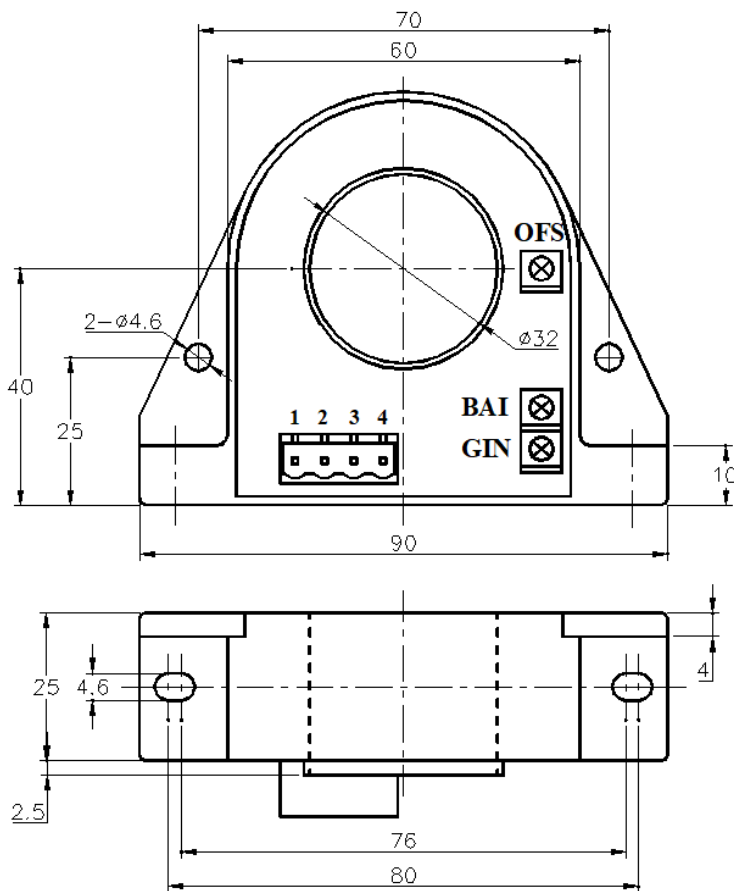


Current Output:

- 1(+): Vcc
- 2(Io): Current Output
- 3(N): NC
- 4(G): GND

$$R_m \leq 80 - 650\Omega$$

PIN Definition and Dimensions - Phoenix Connector 5.08



OFS: Offset Adjustment
BAI: Accuracy adjustment

GIN: Gain Adjustment

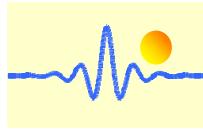
Phoenix Connector 5.08

Voltage output:

- 1(+): Vcc
- 2(N): NC
- 3(O): Output
- 4(G): GND

Current Output:

- 1(+): Vcc
- 2(Io): Current output
- 3(N): NC
- 4(G): GND



Notes:

1. Connect the terminals of power source, output respectively and correctly, never make wrong connection.
2. Two potentiometers can be adjusted, only, if necessary, by turning slowly to the required accuracy with a small screwdriver.
3. The best accuracy can be achieved when the window is fully filled with busbar (current carrying conductor).
4. The in-phase output can be obtained when the direction of current of current carrying conductor is the same as the direction of arrow marked on the transducer